#### Copyright (C) 2011 David K. Levine

This document is an open textbook; you can redistribute it and/or modify it under the terms of version 1 of the open text license amendment to version 2 of the GNU General Public License. The open text license amendment is published by Michele Boldrin et al at http://levine.sscnet.ucla.edu/general/gpl.htm; the GPL is published by the Free Software Foundation at <u>http://www.gnu.org/copyleft/gpl.html</u>.

If you prefer you may use the Creative Commons attribution license http://creativecommons.org/licenses/by/2.0/

# Long Run versus Short Run Player

a fixed simultaneous move stage game

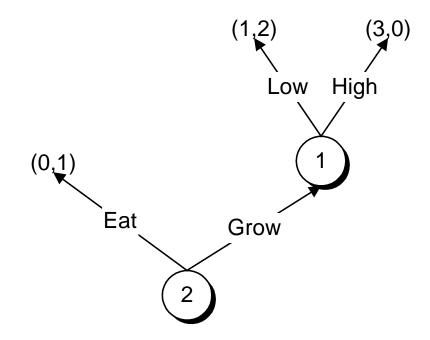
Player 1 is long-run with discount factor  $\delta$ actions  $a^1 \in A^1$  a finite set utility  $u^1(a^1, a^2)$ 

Player 2 is short-run with discount factor 0 actions  $a^2 \in A^2$  a finite set utility  $u^2(a^1, a^2)$ 

the "short-run" player may be viewed as a kind of "representative" of many "small" long-run players

- the "usual" case in macroeconomic/political economy models
- the "long run" player is the government
- ♦ the "short-run" player is a representative individual





#### Example 2: Backus-Driffil

	Low	High
Low	0,0	-2,-1
High	1,-1	-1,0

Inflation Game: LR=government, SR=consumers

consumer preferences are whether or not they guess right

	Low	High
Low	0,0	0,-1
High	-1,-1	-1,0

with a hard-nosed government

#### Repeated Game

history  $h_t = (a_1, a_2, ..., a_t)$ 

null history  $h_0$ 

behavior strategies  $\alpha_t^i = \sigma^i(h_{t-1})$ 

long run player preferences average discounted utility

$$(1-\delta)\sum_{t=1}^{T}\delta^{t-1}u^{i}(a_{t})$$

note that average present value of 1 unit of utility per period is 1

#### Equilibrium

Nash equilibrium: usual definition – cannot gain by deviating Subgame perfect equilibrium: usual definition, Nash after each history Observation: the repeated static equilibrium of the stage game is a subgame perfect equilibrium of the finitely or infinitely repeated game

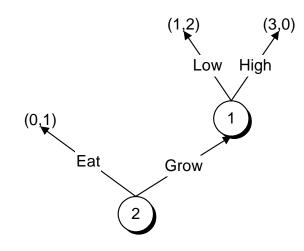
strategies: play the static equilibrium strategy no matter what

"perfect equilibrium with public randomization"

may use a public randomization device at the beginning of each period to pick an equilibrium

key implication: set of equilibrium payoffs is convex

# **Example: Peasant-Dictator**



### normal form: unique Nash equilibrium high, eat

	eat	grow
low	0*,1	1,2*
high	0*,1*	3*,0

payoff at static Nash equilibrium to LR player: 0

precommitment or Stackelberg equilibrium precommit to low get 1 mixed precommitment to 50-50 get 2

minmax payoff to LR player: 0

utility to long-run player

```
mixed precommitment/Stackelberg = 2
best dynamic equilibrium = ?
pure precommitment/Stackelberg = 1
Set of dynamic
equilibria
static Nash = 0
worst dynamic equilibrium = ?
minmax = 0
```

**Repeated Peasant-Dictator** 

finitely repeated game final period: high, eat, so same in every period

Do you believe this??

Infinitely repeated game

begin by low, grow

if low, grow has been played in every previous period then play low, grow

otherwise play high, eat (reversion to static Nash)

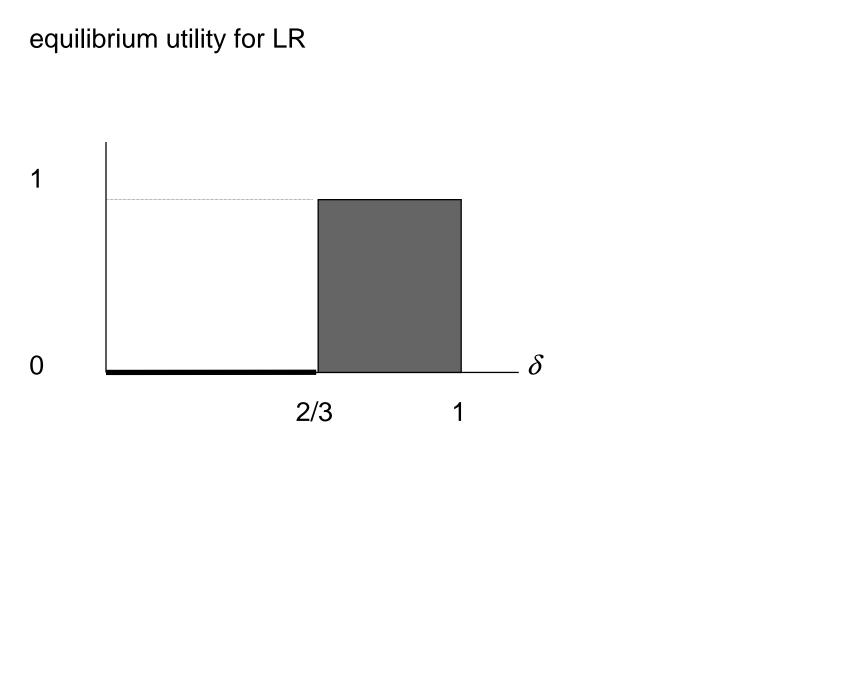
claim: this is subgame perfect

clearly a Nash equilibrium following a history with high or eat SR play is clearly optimal

for LR player may high and get or low and get 1

so condition for subgame perfection

$$(1 - \delta)3 \le 1$$
$$\delta > 2/3$$



# General Deterministic Case (Fudenberg, Kreps and Maskin)

 $+\max u^{1}(a)$ 

\_ mixed precommitment/Stackelberg

 $\overline{v}^1$  best dynamic equilibrium

-pure precommitment/Stackelberg

Set of dynamic equilibria

```
static Nash
```

 $-\underline{v}^1$  worst dynamic equilibrium

```
+ minmax
```

 $+\min u^1(a)$ 

Characterization of Equilibrium Payoff  $\alpha = (\alpha^1, \alpha^2)$  where  $\alpha^2$  is a b.r. to  $\alpha^1$ 

 $\alpha$  represent play in the first period of the equilibrium

 $w^{1}(a^{1})$  represents the equilibrium payoff beginning in the next period

$$v^{1} \ge (1 - \delta)u^{1}(a^{1}, \alpha^{2}) + \delta w^{1}(a^{1})$$
  

$$v^{1} = (1 - \delta)u^{1}(a^{1}, \alpha^{2}) + \delta w^{1}(a^{1}), \alpha^{1}(a^{1}) > 0$$
  

$$\underline{v}^{1} \le w^{1}(a^{1}) \le \overline{v}^{1}$$

strategy: impose stronger constraint using n static Nash payoff for best equilibrium  $n \le w^1(a^1) \le \overline{v}^1$ for worst equilibrium  $\underline{v}^1 \le w^1(a^1) \le n$ avoids problem of best depending on worst remark: if we have static Nash = minmax then no computation is neede for the worst, and the best calculation is exact.

max problem  
fix 
$$\alpha = (\alpha^1, \alpha^2)$$
 where  $\alpha^2$  is a b.r. to  $\alpha^1$   
 $\overline{v}^1 \ge (1 - \delta)u^1(a^1, \alpha^2) + \delta w^1(a^1)$   
 $\overline{v}^1 = (1 - \delta)u^1(a^1, \alpha^2) + \delta w^1(a^1), \alpha^1(a^1) > 0$   
 $n^1 \le w^1(a^1) \le \overline{v}^1$ 

how big can  $w^1(a^1)$  be in = case?

Biggest when  $u^1(a^1, \alpha^1)$  is smallest, in which case  $w^1(a^1) = \overline{v}^1$  $\overline{v}^1 = (1 - \delta)u^1(a^1, \alpha^2) + \delta \overline{v}^1$ 

conclusion for fixed  $\alpha$ 

 $\min_{a^1|\alpha(a^1)>0} u^1(a^1,\alpha^2)$ 

### i.e. worst in support

$$\overline{v}^1 = \max_{\alpha^2 \in BR^2(\alpha^1)} \min_{a^1 \mid \alpha(a^1) > 0} u^1(a^1, \alpha^2)$$

observe:

mixed precommitment  $\geq \overline{v}^1 \geq$  pure precommitment

### Peasant-Dictator Example

	eat	grow
low	0*,1	1,2*
high	0*,1*	3*,0

<i>p</i> (low)	BR	worst in support
1	grow	1
<sup>1</sup> / <sub>2</sub> < <i>p</i> <1	grow	1
p=1/2	any mixture	$\leq 1$ (low)
0 <p<1 2<="" td=""><td>eat</td><td>0</td></p<1>	eat	0
p=0	eat	0

check: 
$$w^{1}(a^{1}) = \frac{\overline{v}^{1} - (1 - \delta)u^{1}(a^{1}, \alpha^{2})}{\delta} \ge n^{1}$$

as  $\delta \to 1$  then  $w^1(a^1) \to \overline{v}^1 \ge n^1$ 

min problem fix  $\alpha = (\alpha^1, \alpha^2)$  where  $\alpha^2$  is a b.r. to  $\alpha^1$   $\underline{v}^1 \ge (1 - \delta)u^1(a^1, \alpha^2) + \delta w^1(a^1)$  $\underline{v}^1 \le w^1(a^1) \le n^1$ 

Biggest  $u^1(a^1, \alpha^1)$  must have smallest  $w^1(a^1) = \underline{v}^1$ 

$$\underline{v}^{1} = (1 - \delta)u^{1}(a^{1}, \alpha^{2}) + \delta \underline{v}^{1}$$

conclusion

$$\underline{v}^1 = \max u^1(a^1, \boldsymbol{\alpha}^2)$$

or

$$\underline{v}^{1} = \min_{\alpha^{2} \in BR^{2}(\alpha^{1})} \max u^{1}(a^{1}, \alpha^{2})$$

that is, constrained minmax

# Example

	L	Μ	R
U	0,-3	1,2	0,3
D	0,3*	2,2	0,0

static Nash gives 0

minmax gives 0

worst payoff in fact is 0

pure precommitment also 0

mixed precommitment

p is probability of up

to get more than 0 must get SR to play M  $-3p + (1-p)3 \le 2$  and  $3p \le 2$ 

```
first one

-3p + (1-p)3 \le 2
-3p - 3p \le -1
```

 $p \ge 1/6$ 

second one

 $3p \le 2$  $p \le 2/3$ 

```
want to play D so take p = 1/6
```

get 1/6 + 10/6 = 11/6

```
utility to long-run player
```

 $+\max u^1(a)=2$ 

```
mixed precommitment/Stackelberg=11/16
```

```
\overline{v}^1 best dynamic equilibrium=1
```

```
pure precommitment/Stackelberg=0
```

Set of dynamic equilibria

```
+static Nash=0
```

 $\underline{v}^1$  worst dynamic equilibrium=0

```
_minmax=0
```

```
_min u^{1}(a)=0
```

calculation of best dynamic equilibrium payoff

### p is probability of up

р	$BR^2$	worst in support
<1/6	L	0
1/6< <i>p</i> <5/6	М	1
p>5/6	R	0

so best dynamic payoff is 1